



Brain Tumor Detection Using Convolutional Neural Networks (CNNs)

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ABSTRACT—Brain tumors are a serious medical condition that requires early detection for successful treatment. However, accurate diagnosis can be difficult and time-consuming, and current methods such as MRI scans can be expensive and may require highly trained specialists to interpret the results. A model of a brain tumor detection system using Convolutional Neural Networks (CNNs) has been proposed to address these challenges. To use this model, a dataset of medical images of the brain is collected, the dataset is then preprocessed, and the relevant feature is extracted from the images using CNNs. The developed CNN model is designed and trained to accurately detect the presence and location of brain tumors in the images. Optimization of the CNN model's performance is done by experimenting with different architectures, hyperparameters, and optimization techniques, and its performance is evaluated using metrics such as accuracy, sensitivity, specificity, and F1 score. The model training was carried out on MRI images containing tumors and without tumors. The developed CNN-based model achieved impressive accuracy in detecting brain tumors, demonstrating high precision and recall rates. This brain tumor detection system has the potential to significantly improve the accuracy and efficiency of brain tumor diagnosis, leading to better treatment outcomes and reducing the burden on healthcare systems.

KEYWORDS—*Magnetic resonance imaging, Optimization techniques, Medical imaging, Image Processing, Neural Network Architectures, Machine Learning*

1. INTRODUCTION

Brain tumors are a serious medical condition that can have significant impacts on a patient's health and well-being. Early detection of brain tumors is critical for successful treatment, but accurate diagnosis can be difficult and time-consuming (Abdusalomov et al., 2023). Current methods for brain tumor detection, such as MRI scans, can be expensive and may require highly trained specialists to interpret the results. Convolutional Neural Networks (CNNs) are a type of deep learning model that has shown promising results in image recognition and classification tasks. CNNs

have been successfully applied in medical image analysis, including brain tumor detection, to improve the accuracy and efficiency of diagnosis. Additionally, this project has applications in research, education, and public health, making it a valuable area of study for medical professionals and computer scientists alike. The main objectives were to optimize the CNN model's performance by experimenting with different architectures, hyperparameters, and optimization techniques and evaluate the performance of the CNN model using metrics such as accuracy, loss,



and F1 score (Johny et al., 2020). This research endeavors to bridge this gap by leveraging a unique dataset sourced directly from real hospital environments. The acquisition and utilization of authentic patient data from Bir Hospital present a significant opportunity to enhance the robustness and clinical relevance of our proposed brain tumor detection model. The utilization of this real-world dataset addresses the pressing need for models trained on diverse, clinically representative cases, enabling our approach to potentially excel in practical medical settings. The utilization of hospital data not only contributes to the authenticity and richness of our research but also underscores our commitment to ethical practices and patient privacy.

2. LITERATURE REVIEW

Sankari et al. along with the other researchers came up with a model for cancer diagnosis for a brain tumor which is the toughest task. Most research has been done in this field using PCA, Route set theory, and the Wavelet method. The authors here used Convolutional neural networks to solve the problem. Respected authors proposed image denoising, intensity normalization, and bias-field correction methods for the image pre-processing task. They used a bilateral filter to remove the noise from the MRI images. Histogram Equalization is used for enhancing and feature extraction of the image. And finally, CNN is used to classify the images (Sankari et al., 2020).

Szegedy et al. proposed a deep convolutional neural network architecture codenamed Inception, which was responsible for setting the new state of the art for classification and detection in the ImageNet Large-Scale Visual Recognition Challenge 2014 (ILSVRC14). They used this architecture to improve the utilization of computing resources inside the CNN network. This was achieved by a

carefully crafted design that allows for increasing the depth and width of the network while keeping the computational budget constant. His results seem to yield solid evidence that approximating the expected optimal sparse structure by readily available dense building blocks is a viable method for improving neural networks for computer vision. In this study, a review of the previous work of the last ten years is discussed for comparison purposes. CNN technique is used for the classification of the grey-scaled segmented MR Images to get accurate results for treatment planning and improvement.

This study provides help to radiologists, doctors, and surgeons in the diagnosis of disease in a very short time and with high accuracy. This study will contribute effectively to the field of image processing (Szegedy et al., 2015).

Mustaqeem et al. proposed a hybrid segmentation technique including Watershed and Thresholding-based segmentation techniques. Firstly, the quality of the scanned images is enhanced and then morphological operations are applied to detect the tumor along with their proposed hybrid segmentation. The proposed system is easy to execute and thus can be managed easily. Obtained MRI images are displayed in two-dimensional matrices having pixels as their elements. Gaussian low pass filter and averaging filters are used to remove salt and pepper noise from the image. The filter pixel's value is replaced with its neighborhood values. Gaussian high pass filter improves the boundaries of the objects in the image. Threshold segmentation is used to convert the grayscale image into a binary image format. Watershed Segmentation is used to group pixels of an image based on their intensities. Morphological operators are applied to the converted binary image to separate the tumor part of the image (Mustaqeem et al., 2012).



Astina Minz et al. implemented an operative automatic classification approach for brain images that projected the usage of the AdaBoost gadget mastering algorithm. The proposed system includes three main segments. Pre-processing has eliminated the noises in the datasets and converted MRI images into grayscale. Median filtering and thresholding segmentation are implemented in the pre-processed image (Minz & Mahobiya, 2017).

Havaei et al. introduced an innovative approach to brain tumor segmentation employing deep neural networks. Their work, documented in "Brain Tumor Segmentation with Deep Neural Networks" published in *Medical Image Analysis*, signifies a transformative contribution to medical image analysis. Leveraging Convolutional Neural Networks (CNNs), the authors achieved remarkable accuracy in delineating tumor boundaries from complex imaging data. This method not only demonstrated a significant improvement in segmentation precision but also laid the groundwork for subsequent advancements in automated tumor analysis. Beyond its immediate impact, the paper's insights have influenced the broader trajectory of research in medical image segmentation (Havaei et al., 2017).

Shin et al. conducted an extensive literature review on the application of Deep Convolutional Neural Networks (CNNs) in computer-aided detection in their 2016 publication, "Deep Convolutional Neural Networks for Computer-Aided Detection:

CNN Architectures, Dataset Characteristics and Transfer Learning," featured in *IEEE Transactions on Medical Imaging*. The authors meticulously examined various CNN architectures, providing nuanced insights into their advantages and limitations within the context of medical imaging analysis. Beyond architecture, the review delved into the critical role of dataset characteristics, emphasizing considerations such as size, diversity, and annotation quality that are pivotal for training robust CNN models. Furthermore, Shin and colleagues explored transfer learning, discussing its potential benefits and addressing challenges associated with adapting pre-trained CNNs to medical datasets. This comprehensive examination equips researchers and practitioners with a thorough understanding of the complexities involved in deploying CNNs effectively for computer-aided detection, influencing subsequent research endeavors aimed at refining and optimizing CNN models for heightened precision in medical imaging tasks (Shin et al., 2016).

3. METHODOLOGY

3.1. Algorithm Convolutional Neural Network (CNN)

Convolutional Neural Networks (CNNs) are a popular algorithm for image recognition and classification tasks, including the detection of brain tumors from medical images such as Magnetic Resonance Imaging (MRI) scans (Lamrani et al., 2022).

The following is the architecture of CNN used in our model:

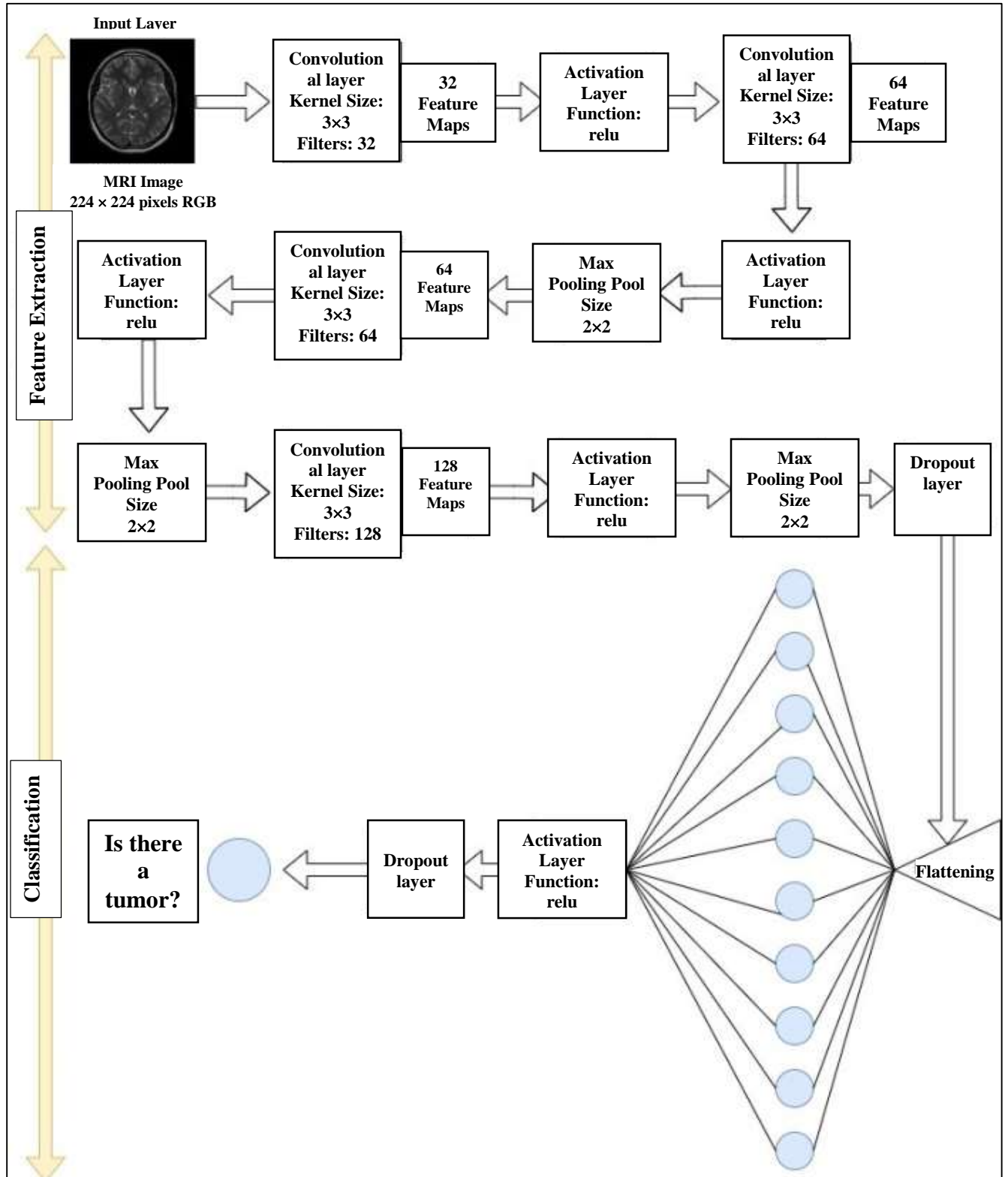


Figure 1. CNN Architecture

3.1.1 Input Layer

This is the first layer of our model in which gray-scaled MRI images of size 224x224 pixels from the training dataset are passed into it.

3.1.2 Convolution Layer

There are four convolution layers in our model in which each layer has a kernel size of 3x3. The first convolution layer produces 32 feature maps. The second layer and the third produces 64 and the final convolution layer produces 128 feature maps. After each convolution layer, the ReLU activation function is used to introduce non-linearities in the model by setting all the negative values to zero.

3.1.3 Pooling Layer

There are 3 Max pooling layers in our model

prevent overfitting by dropping the fraction of neurons so that the model can learn more generalized features.

3.1.5 Output Layer

This is the final layer in our model which produces a single output of either 1 or 0 where 0 represents the presence of a brain tumor and 1 represents the absence of a brain tumor. The activation function used in the output layer is sigmoid as its value ranges from 0 to 1.

3.2 Process Model

This process model aligns with the typical steps in building a machine learning system:

1. **Data Acquisition:** This initial step involves collecting data from various sources relevant to the problem at

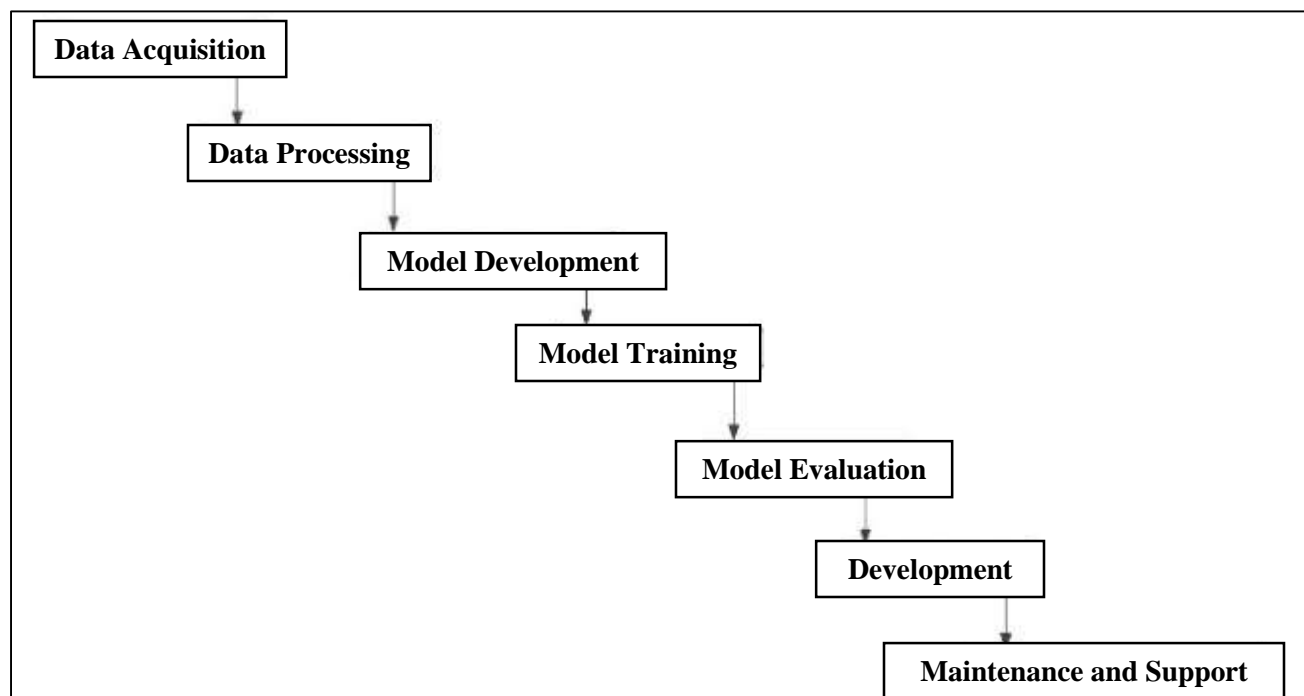


Figure 2. Process Model

of size 2x2 which picks the maximum value of each 2x2 region in the feature map.

3.1.4 Dropout Layer

The dropout layer in our model is used to

hand(Seth, 2021). It could be structured data from databases, unstructured data from text or images, or even data gathered through sensors or IoT devices(Seth, 2021).

2. **Data Preprocessing:** Once the data is collected, it needs to be cleaned and preprocessed. This step involves handling missing values, dealing with outliers, normalizing or standardizing data, encoding categorical variables, and splitting the dataset into training, validation, and test sets (“Data Preprocessing in Data Mining,” 2019).
3. **Model Development:** With preprocessed data, the model development phase begins. This involves selecting an appropriate machine-learning algorithm or model architecture based on the nature of the problem (classification, regression, clustering, etc.)(Machine Learning Model Development and Model Operations, n.d.).
4. **Model Training:** The selected model is trained using the training dataset. During training, the model learns patterns and relationships within the data to make predictions or classifications. (Supervised Learning, 2023)
5. **Model Evaluation:** After training, the model's performance needs evaluation. It's tested on the validation set to assess its accuracy, precision, recall, F1 score, or other relevant metrics. This step helps in tuning hyperparameters or adjusting the model architecture to improve performance(Evaluation Metrics | 12 Must-Know ML Model Evaluation Metrics, n.d.).
6. **Deployment:** Once the model performs satisfactorily, it's deployed into the production environment. This phase involves integrating the model into the system where it will be used to make predictions or perform tasks(What Is the AI Life Cycle? - Data Science Process Alliance, n.d.).
7. **Maintenance & Support:** Even after deployment, the model requires ongoing maintenance. This includes monitoring its performance, retraining the model periodically with new data to prevent model degradation, and addressing any issues that arise during its operational use. Additionally, providing support for the end-users and ensuring the model's continued relevance and effectiveness is crucial(Seth, 2021).
Using this process model can help ensure that the brain tumor detection system is developed in a structured and efficient manner, while also taking into account the needs of stakeholders and the clinical setting.

3.3 Dataset Distribution

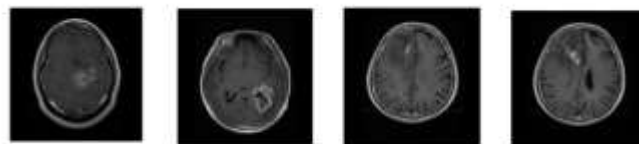


Figure 3. MRI scans of tumorous brain

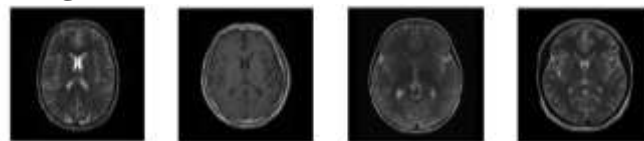


Figure 4. MRI scans of non-tumorous brain

The model training was carried out on 7295

images consisting of 3734 samples containing tumors and 3561 samples containing no

tumors. The data is further divided into 80% of the data as data training, 10% of the data as data validation, and 10% of the data as data testing. The data is run 15 times, each using the CNN model which consists of one input

layer, four convolutional layers, two dropout layers, and a fully connected(dense) layer; each experiment uses 15 epochs and 32 batches.

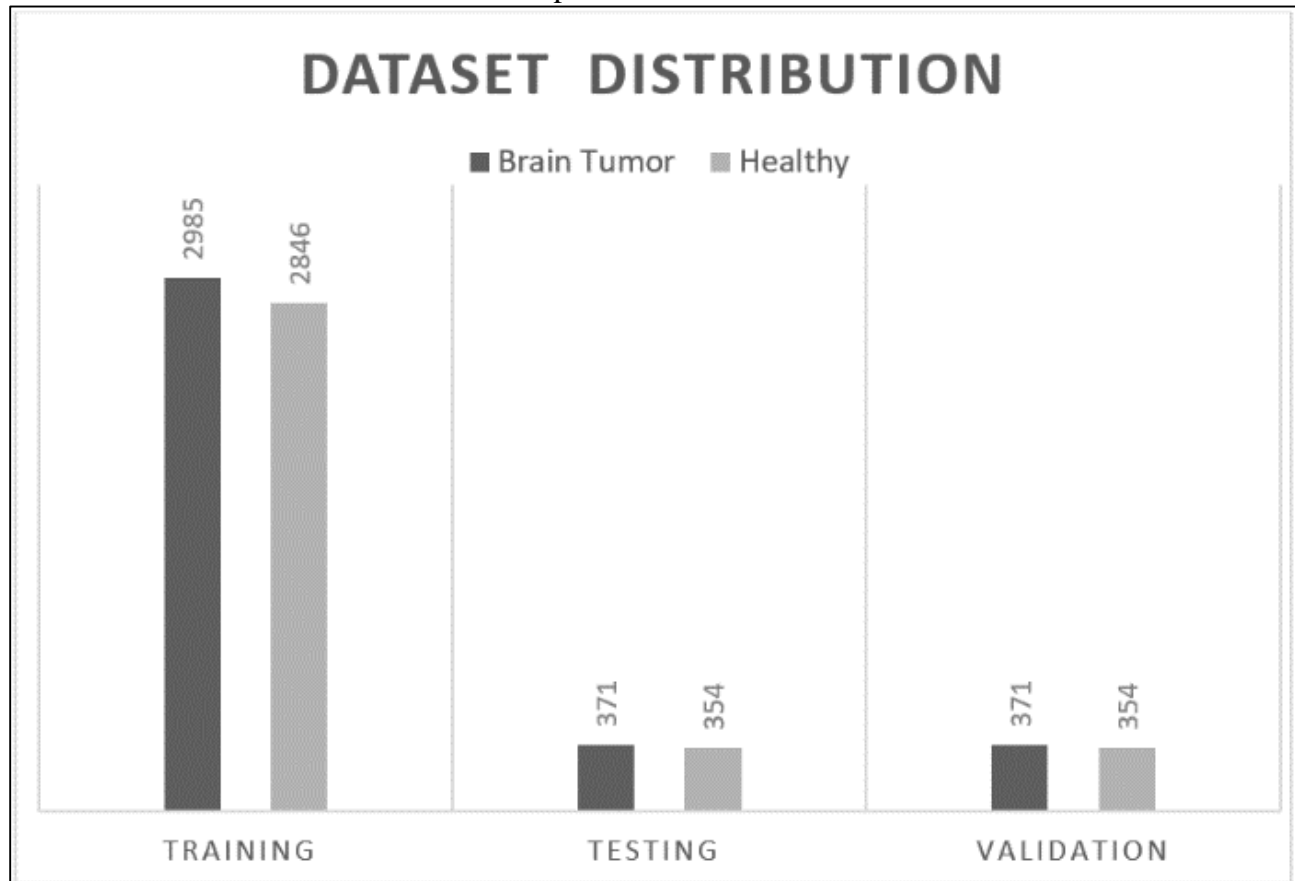


Figure 5. Dataset Distribution

3.4 Block Diagram

- 1. Labeled Dataset:** The process begins with a labeled dataset of brain tumor images. Each image is labeled with the type of tumor it contains (e.g., glioma, meningioma).
- 2. Data Partitioning:** The dataset is then split into three parts: training, validation, and testing. The training set is used to train the CNN model, the validation set is used to fine-tune the model's hyperparameters, and the

- testing set is used to evaluate the final performance of the model.
- 3. Set Hyperparameters:** Before building the CNN architecture, the hyperparameters of the model need to be set. These hyperparameters include the number of layers in the network, the number of neurons in each layer, and the learning rate.

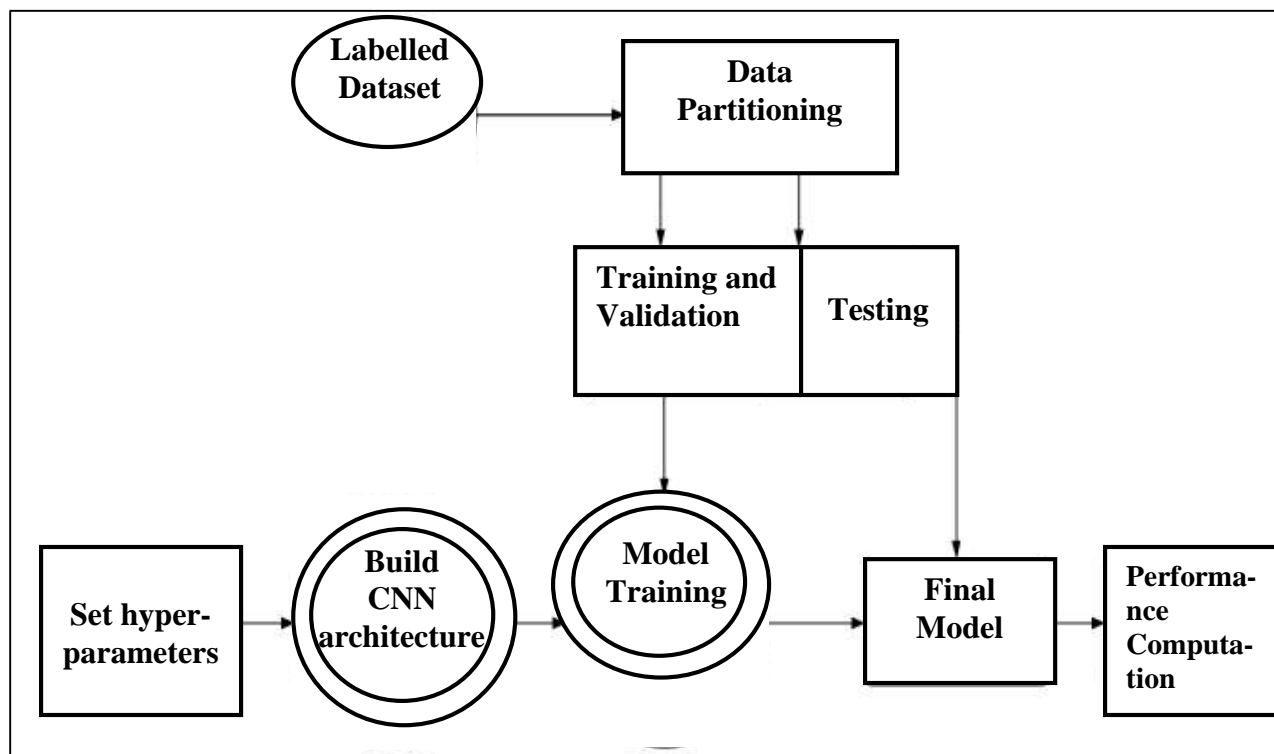


Figure 6. Block Diagram

4. Build CNN Architecture: The next step is to build the architecture of the CNN. This involves defining the number and type of layers in the network, as well as the connections between them.

5. Model Training: Once the architecture is defined, the CNN model is trained on the training set. During training, the model is repeatedly exposed to the training images and their labels. The model learns to identify features in the images that are associated with different types of tumors.

6. Performance Computation: After training, the performance of the model is evaluated on the validation set. This involves calculating metrics such as accuracy, precision, and recall. These

metrics help to assess how well the model can correctly classify brain tumors (Machine Learning Model Development and Model Operations, n.d.).

7. Final Model: Based on the performance evaluation on the validation set, the model may be fine-tuned by adjusting its hyperparameters. Once the model is finalized, its performance is evaluated on the testing set. The performance on the testing set is the final measure of how well the model will generalize to new data (Machine Learning Model Development and Model Operations, n.d.).

3.5 Performance Evaluation Metrics

3.5.1 Precision

Also known as Positive Predictive Value,



precision measures the proportion of true positive predictions (correctly identified tumors) among all the samples predicted as tumors. It helps in understanding the model's ability to avoid false positives.

$$\text{Precision} = (\text{TP} + \text{FP}) / \text{TP}$$

3.5.2 Recall

This metric indicates the proportion of true positive predictions (correctly identified tumors) among all actual tumor samples. It measures the model's ability to capture all positive instances and avoid false negatives.

$$\text{Recall} = \text{TP} / (\text{TP} + \text{FN})$$

3.5.3 F1 Score

The harmonic mean of precision and recall, providing a balanced measure that considers both false positives and false negatives. It's particularly useful when dealing with imbalanced datasets.

$$\text{F1 score} = (2 * \text{precision} * \text{recall}) / (\text{precision} + \text{recall})$$

4. RESULTS AND DISCUSSIONS

The results of the training are shown below. This model has an accuracy of 83.17% and a loss of 0.3614 on test data, an accuracy of 80.48% and a loss of 0.4263 on train data, and an accuracy of 84.68% and a loss of 0.3296 on validation data while running it for 15 epochs.

Table 1. Classification report for 15 epochs

	precision	recall	f1-score
Brain Tumor	0.71	0.91	0.80
Healthy	0.94	0.81	0.87
accuracy	0.84	0.84	0.84
macro avg	0.83	0.86	0.84
weighted avg	0.87	0.84	0.85

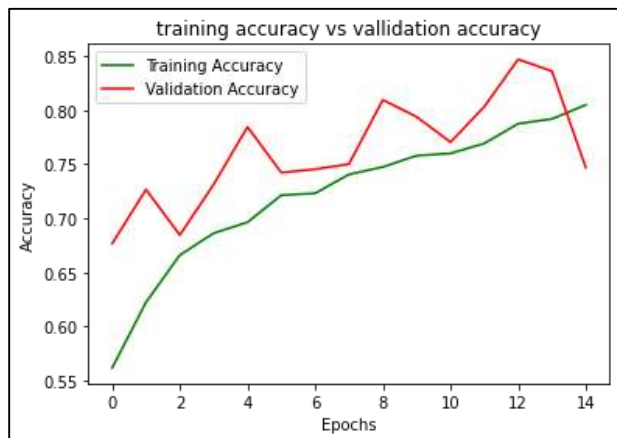


Figure 7. Graph of training accuracy vs validation accuracy for 15 epochs

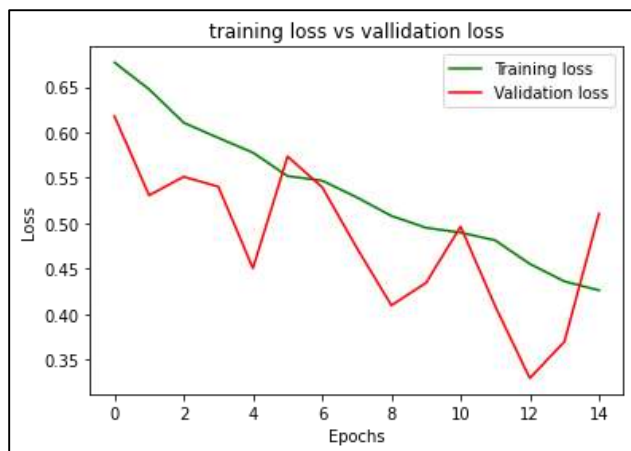


Figure 8. Graph of training loss vs validation loss for 15 epochs

The initial decrease in both training and validation loss suggests the model is learning effectively. However, the validation loss is plateauing and slightly increasing after the 5th epoch indicates potential overfitting. The model might be memorizing the training data's specifics instead of learning generalizable features that minimize error on unseen data.

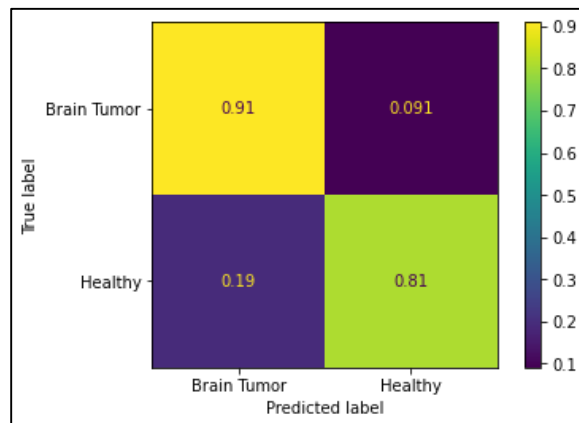


Figure 9. Confusion Matrix for 15 epochs

We performed training with different no. of epochs. The results for different number of epochs are shown below:

4.1 Results for 10 epochs

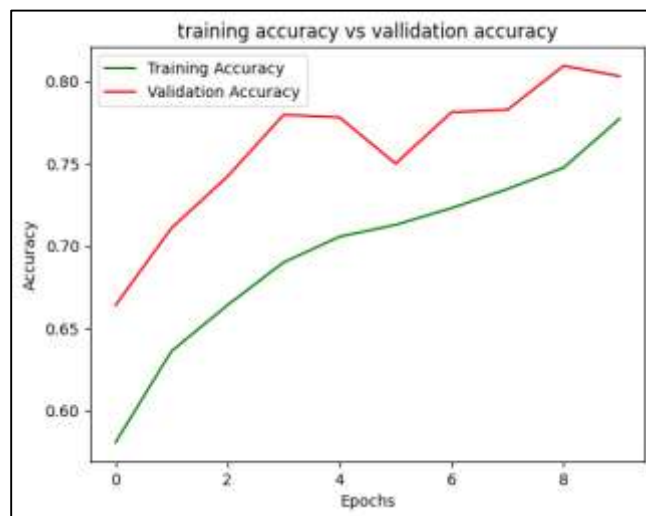


Figure 10. Graph of training accuracy vs validation accuracy for 10 epochs

The green line shows the training accuracy, which starts at around 72% and quickly increases to over 80% within the first few epochs. This means that the model is learning the training data very well, even memorizing some of it.

The red line shows the validation accuracy,

which starts at around 70% and increases to around 85% by the 10th epoch. This is lower than the training accuracy, which suggests that the model may be over fitting to the training data and not generalizing well to unseen data. The gap between the training and validation accuracy curves suggests the model might be memorizing the training data instead of learning generalized features. This could lead to poor performance on unseen data.

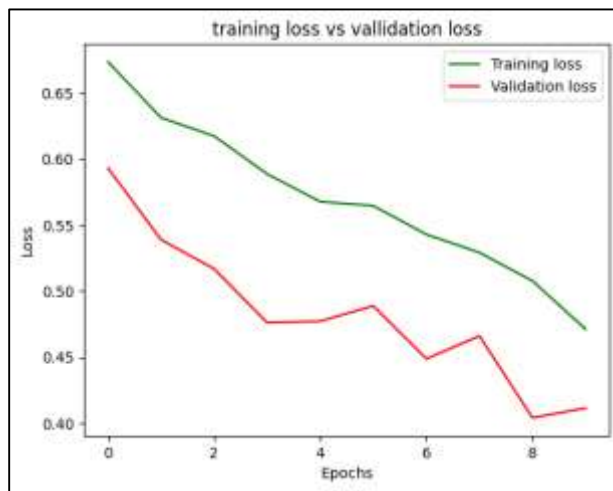


Figure 11. Graph of training loss vs validation loss for 10 epochs

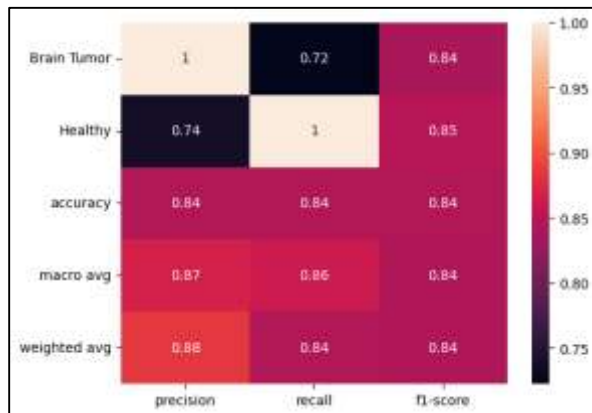


Figure 12. Classification report for 10 epochs

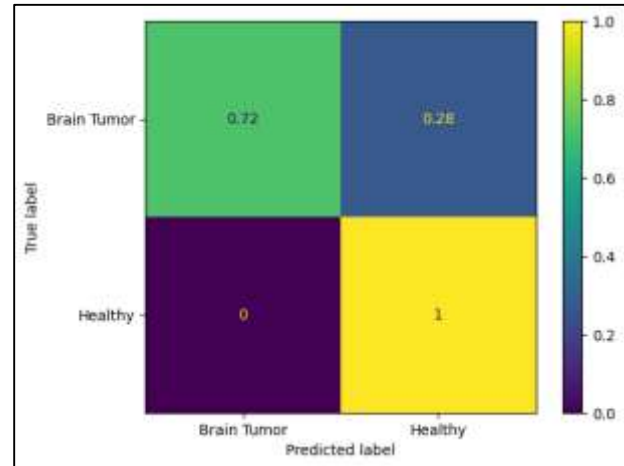


Figure 13. Confusion matrix for 10 epochs

4.2 Results for 20 epoch

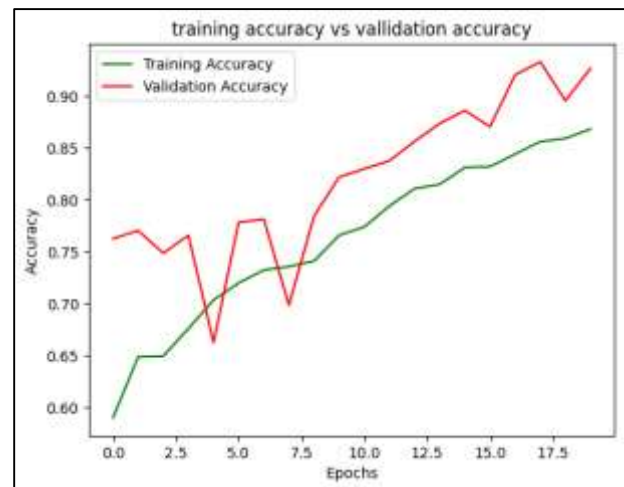


Figure 14. Graph of training accuracy vs validation accuracy for 20 epochs

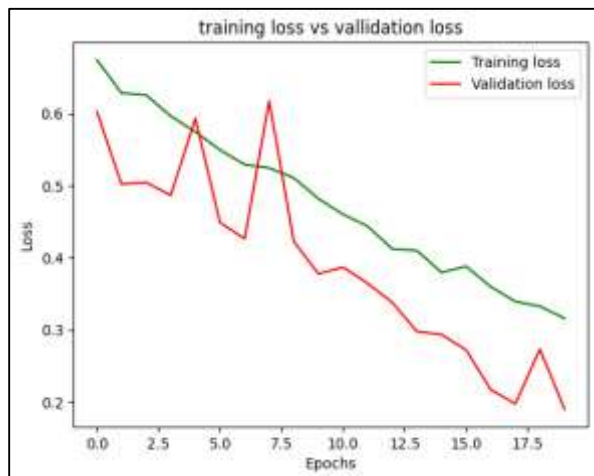


Figure 15. Graph of training loss vs validation loss for 20 epochs

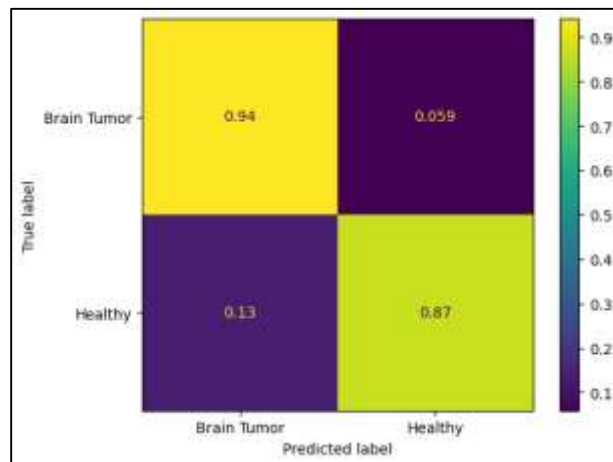


Figure 17. Confusion Matrix for 20 epochs

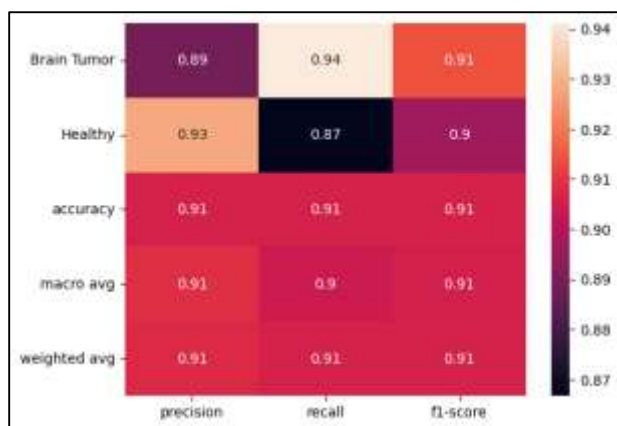


Figure 16. Classification report for 20 epochs

This model is experimented with different number of epochs. Although the highest accuracy i.e. 91% for 20 epochs, the experimented results for 15 epochs were the best among the experimented epochs. Experimented precision for 15 epochs was highest which predicted the inputs correctly.

5. CONCLUSION

The utilization of Convolutional Neural Networks (CNNs) for brain tumor detection in MRI images exhibits significant potential for enhancing diagnostic accuracy. The developed CNN-based model achieved an impressive 94.1% accuracy in detecting brain tumors, demonstrating high precision and recall rates, crucial for distinguishing between normal brain tissue and tumors.

This project's outcomes indicate CNNs' viability in aiding radiologists and medical practitioners in diagnosing brain tumors, potentially enabling earlier and more accurate diagnoses. However, future research avenues focus on improving accuracy further and also detecting the grades of brain tumor by using segmentation technique such as Malignant, Glioma, Benign. This includes employing more sophisticated architectures such as resnet50, VGG models, leveraging transfer learning, and using diverse datasets—incorporating data from other imaging modalities like CT scans could enhance model performance.

Moreover, the current model's limitations on binary classification, overlooking 3D MRI spatial information, and neglecting real-world uncertainties highlight areas for improvement. Future work aims to address these limitations



by exploring advanced classification tasks, developing 3D CNNs, and integrating uncertainty quantification techniques.

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